



sensors



Communication

Wideband Array Signal Processing with Real-Time Adaptive Interference Mitigation

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Outline

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What is Spatial Filtering?



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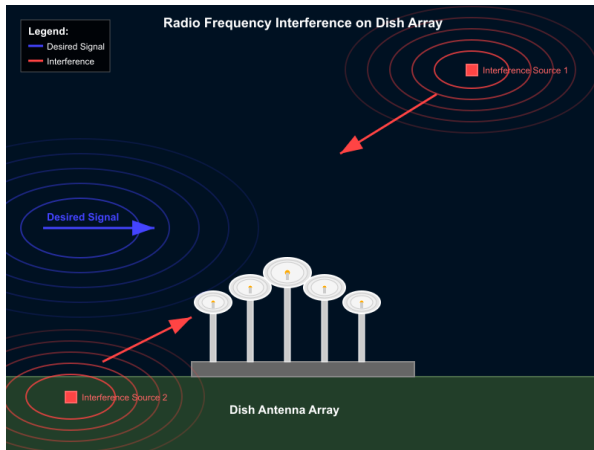
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Definition

Spatial filtering is the study of using a known array spatial geometry to enhance or suppress signals arriving from specific directions to the array.

The Problem

- ▶ Radio Frequency Interference (RFI) is a problem! How can we recover as much of the celestial signal as possible?



Credit: Claude for base SVG code

The Problem

- ▶ Radio Frequency Interference (RFI) is a problem! How can we recover as much of the celestial signal as possible?
- ▶ Can we do this fast enough in real time on GPUs?
 - ▶ Raw voltage streams are not saved at fine resolution - this cannot be done offline.



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The Problem

- ▶ Radio Frequency Interference (RFI) is a problem! How can we recover as much of the celestial signal as possible?
- ▶ Can we do this fast enough in real time on GPUs?

This Paper

- ▶ Currently the most developed RFI-mitigation system via spatial filtering on GPUs.
- ▶ Presents a proof-of-concept system for a 4x4 Phased Array Feed in a laboratory setting.
- ▶ Shows that this system works for both a moving narrowband RFI tone and a 50 kHz bandwidth moving wideband RFI tone.



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Where This Sits in the Literature



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BYU - Green Bank Telescope



Figure: Credit: <https://science.nrao.edu/facilities/gbt>



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Spatial Filtering Playbook

1. Take complex voltage data from n antennas and T time samples to create a data matrix $\mathbf{X}$ with shape $n \times T$.

Example

$$\mathbf{X} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1T} \\ a_{21} & a_{22} & \cdots & a_{2T} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nT} \end{bmatrix} \in \mathbb{C}^{n \times T}$$



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Spatial Filtering Playbook

1. Take complex voltage data from n antennas and T time samples to create a data matrix $\mathbf{X}$ with shape $n \times T$.
2. Form the covariance matrix $\mathbf{C} = \mathbf{X}\mathbf{X}^H$ which is $n \times n$ Hermitian.

Example

$$\mathbf{C} = \begin{bmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1n} \\ \overline{\sigma_{12}} & \sigma_2^2 & \cdots & \sigma_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \overline{\sigma_{1n}} & \overline{\sigma_{2n}} & \cdots & \sigma_n^2 \end{bmatrix}$$



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2. Form the covariance matrix $\mathbf{C} = \mathbf{X}\mathbf{X}^H$ which is $n \times n$ Hermitian.
3. Decompose the matrix using eigendecomposition into the form $\mathbf{C} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^H$.

Example

$$\mathbf{C} = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \cdots & \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} \begin{bmatrix} \mathbf{u}_1^H \\ \mathbf{u}_2^H \\ \vdots \\ \mathbf{u}_n^H \end{bmatrix}$$



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3. Decompose the matrix using eigendecomposition into the form $\mathbf{C} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^H$.
4. Use this to adjust the beamforming weights in order to remove interference:
 - 4.1 Nulling eigenvalues,
 - 4.2 Shrinking eigenvalues,
 - 4.3 Orthogonal / Oblique subspace projection.



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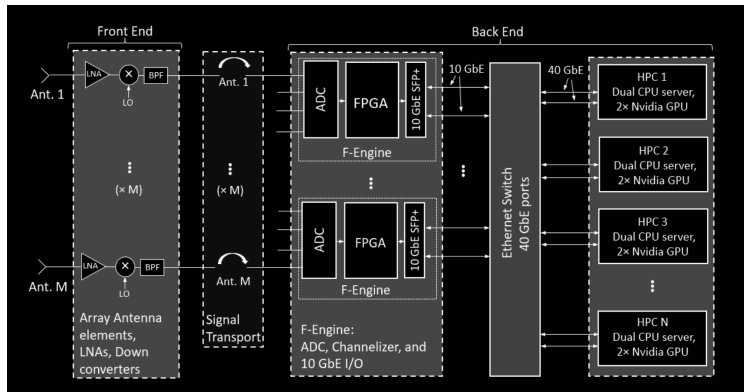
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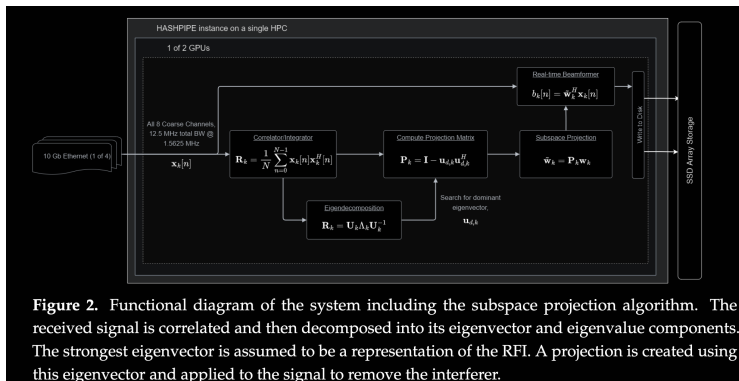
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System Architecture

- Uses a heterogeneous F-XB architecture:
 - F: Fourier transform - done using FPGAs.
 - X: Correlation - done using GPUs.
 - B: Beamforming - done using GPUs.



- Beamforming weights are updated using spatial filtering algorithms after the correlation step.



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System Architecture

- ▶ Uses a heterogeneous F-XB architecture:
 - ▶ F: Fourier transform - done using FPGAs.
 - ▶ X: Correlation - done using GPUs.
 - ▶ B: Beamforming - done using GPUs.
- ▶ Data is sampled every 2.5 ns. Channellization is a 256-point FFT so resolution after channelization is ≈ 640 ns.
- ▶ Original frequency band is centered at 10.2 GHz.
- ▶ Bandwidth is 96 channels of 1.5625 MHz each for total operating bandwidth of 150 MHz. 16 channels are discarded.
- ▶ Weights are updated using 4250 time steps which corresponds to 2.7 ms.



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Narrowband Cancellation

- ▶ Uses a 4x4 grid of antennas in a lab environment.
- ▶ Signal Generators for:
 - ▶ Signal of Interest stationary at array boresight.
 - ▶ Moving RFI signal beginning at 45 degrees to array.
- ▶ Scan duration was 6 seconds and RFI source moved 20 degrees in that time.
 - ▶ At cruising altitude, this is about 3.5x the speed of a plane (235 m/s vs 740 m/s).
 - ▶ For a GPS satellite, this is an order of magnitude faster.
- ▶ Signal-to-Noise Ratio was 25 dB, Interference-to-Noise Ratio was 35 dB.
- ▶ Beamforming weights were unity before filtering weight updates (i.e. no MaxSNR beamforming).



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Narrowband Cancellation Results



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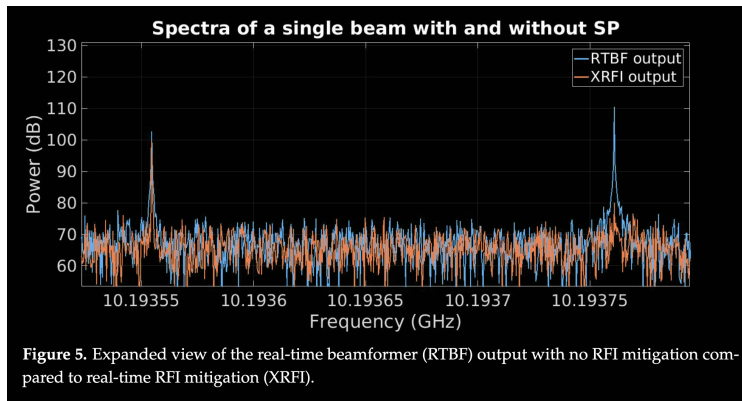
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Wideband Cancellation

- Uses a 50kHz wide modulated signal at a 45 degree angle to signal of interest.



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Wideband Cancellation Results



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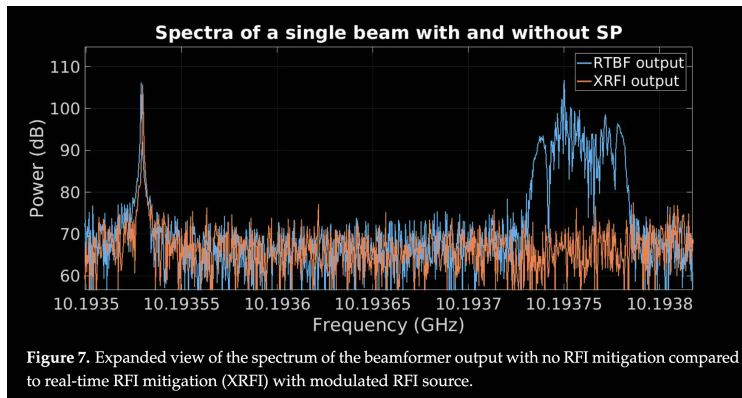
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Is it fast enough?

- ▶ 2.7 ms of data was used for each beamforming weight update.
- ▶ They report that the GPU section of processing was completed in 2.3 ms with active cancellation as opposed to 1.4 ms for only beamforming.
- ▶ No breakdowns are given, and it does not seem like PCIe transfer speed was included in this total, which can be a significant bottleneck (Ruzindana 2021).



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- ▶ Currently it supports only a 16-element phased array feed. ALPACA will have 69 elements when it is installed on GBT in late 2025.
 - ▶ Murriyang CryoPAF has 196!
- ▶ Only one eigenvalue is nulled, higher dimensional spaces with multiple interferers will require more eigenvalues.
 - ▶ It's also assumed that the strongest signal is the interference!
- ▶ Signal of interest and RFI are present in the same coarse channels - what if they are in different channels?
- ▶ How will this affect pulsar searching (see Kocz et al. 2010)? Can we use oblique projection instead (Hellbourg 2012)? Can we do better than oblique projection?



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